

Questions:

Restriction of costs to positive values:

a) Why would an optimal algorithm need to expand the whole space (in case of possible negative rewards) ?
Otherwise the agent cannot guarantee that there are no negative (highly rewarding) paths even in less promising branches.

b) Does a restriction to $c(n,a,n') > \min$ (negative val.) help?

- In case of trees and in case of graphs?

In case of trees: yes, if there is a maximum depth, some branches don't need to be visited as even with maximum reward in the remaining levels, the current best path cannot be improved

In case of graphs: no, loops with negative rewards are possible



Questions:

Restriction of costs to positive values:

- c) Assume there are loops and the world state is the same after a finite number of actions. What is the optimal strategy in case of negative path costs for all actions?
Loop forever, this increases the reward each time.
- d) Are there negative costs in real life?
Yes, e.g., a detour to a cheap gas station can be rewarding



Questions:

True or false? Why?

- a) Depth-first expands always at least as many nodes as A^* with an admissible heuristic

False, depth-first may be lucky to find immediately the optimal path, A^* has to consider alternatives to ensure optimality.

- b) For the 8-puzzle, $h(n) = 0$ is admissible.

True, $h(n) = 0$ is always admissible (h is non-negative and never overestimates).

- c) A^* is not suitable for robotics, because percepts, actions, and states deal with continuous values.

False, the continuous spaces can be discretized. A^* (or variants) are widely used, e.g., for navigation.



Questions:

True or false? Why?

- d) In chess, a rook (Turm) can move only horizontally or vertically, but not jump over other chessmen. The manhattan distance is admissible for a move from A zu B. False, if there are no other chessmen, for a straight line across the chess board one move is sufficient, but the manhattan distance is 7, i.e., the manhattan distance overestimates.



Questions:

In graph-based A*, there can be state spaces with suboptimal solutions if h is admissible, but not consistent. Show an example.

